



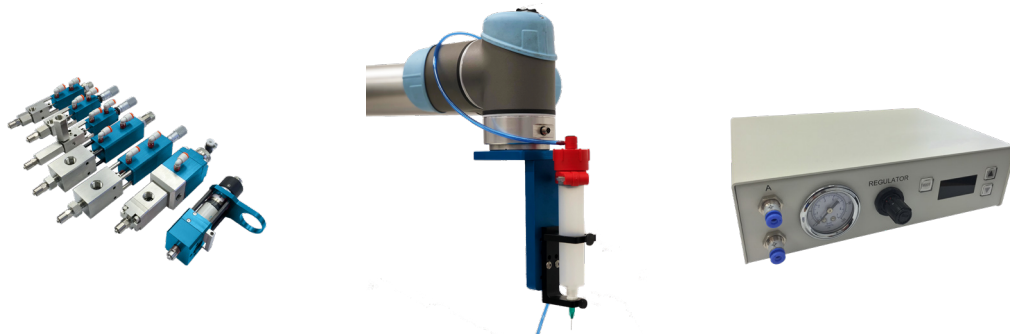
# UNIVERSAL ROBOTS

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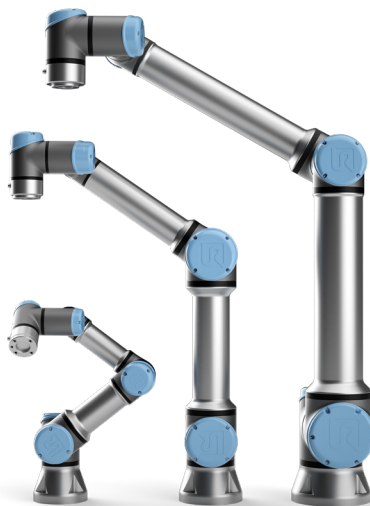


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## PRECISION DISPENSING UR+ SOLUTION TRIAL INSTRUCTIONS



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## PRACTICE TRIAL

### Introduction

Dispensing bead width & quality are effected by supply pressure, robot speed, needle size, and on/off shot timing.

1. Dwell Timing - Sets the initial wait for dispense.
2. Supply Pressure - Increasing pressure increases flow
3. Needle Size - Increased size increases bead width
4. Robot Speed - Increasing speed reduces width & quality

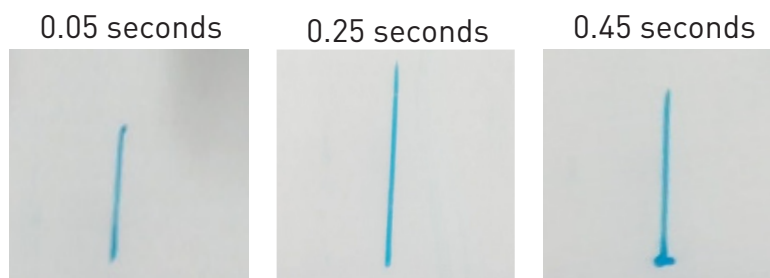
### Trial Setup

We will now run a sample set using the sample material to gain experience with 1-4 (above).

### Trial Test I: Varying Initial Dwell Time

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- 1.) Load syringe with test fluid.
  - 2.) Place dark material surface under robot with Precision Dispense Kit installed.
  - 3.) Install needle size 18G.
  - 3.) Jog robot to start position & about 1/4" above dispense surface
  - 4.) Set control pressure at 10 PSI.
  - 5.) Program start way point to trigger controller on.
  - 6.) Set wait time to 0.25 seconds
  - 7.) Set Set Dispense to be triggered after wait
  - 8.) Jog robot 2" in straight line & program end point to turn off controller.
  - 9.) Set Set Dispense to be triggered off after new point
  - 10.) Set wait time to 0.5 seconds
  - 11.) Set robot speed to 100mm/s .
  - 12.) Run test program 1.
  - 13.) Repeat program with 0.05 seconds and 0.45 seconds.
  - 14.) Review the initial buildup and lack of, tune timing for consistent flow
- Your Results should look like:





### Trial Test II: Varying Needle Size

- 1.) Continue with previous program
  - 2.) Run test program 1.
  - 3.) Repeat program with needle size 20G and needle size 15G.
- Your Results should look like:

18 G



20 G



15G



### Trial Test III: Varying Pressure

- 1.) Continue with previous program
  - 2.) Run test program 1.
  - 3.) Repeat program with 20 PSI and 70 PSI.
- Your Results should look like:

6 psi

10 psi

20 psi





### Trial Test IV: Varying Robot speed

- 1.) Continue with previous program
  - 2.) Run test program 1.
  - 3.) Repeat program with robot speed 50 mm/s and robot speed 150mm/s.
- Your Results should look like:

50 mm/s



100 mm/s



150 mm/s



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